



The Sutton Academy

Knowledge Rich Curriculum Plan

Course/Unit



Lesson/Learning Sequence	Intended Knowledge: <i>Students will know that...</i>	Tiered Vocabulary	Prior Knowledge: <i>In order to know this students, need to already know that...</i>	Assessment																														
<p>LO: To learn how to construct a mechanical model.</p>	<ul style="list-style-type: none"> Students will know how to construct a model, Students will know how sketch a model Students will how to construct a simple model 		<p>Students will need to know how to use formula</p> <p>Students will need to substitute</p>																															
<p>LO: To learn how to use assumptions and units in mechanical models.</p>	<ul style="list-style-type: none"> Students will know what assumptions to make depending on the model. <table border="1" data-bbox="342 448 1111 1225"> <thead> <tr> <th>Model</th> <th>Modelling assumptions</th> </tr> </thead> <tbody> <tr> <td>Particle – Dimensions of the object are negligible.</td> <td> <ul style="list-style-type: none"> mass of the object is concentrated at a single point rotational forces and air resistance can be ignored </td> </tr> <tr> <td>Rod – All dimensions but one are negligible, like a pole or a beam.</td> <td> <ul style="list-style-type: none"> mass is concentrated along a line no thickness rigid (does not bend or buckle) </td> </tr> <tr> <td>Lamina – Object with area but negligible thickness, like a sheet of paper.</td> <td> <ul style="list-style-type: none"> mass is distributed across a flat surface </td> </tr> <tr> <td>Uniform body – Mass is distributed evenly.</td> <td> <ul style="list-style-type: none"> mass of the object is concentrated at a single point at the geometrical centre of the body – the centre of mass </td> </tr> <tr> <td>Light object – Mass of the object is small compared to other masses, like a string or a pulley.</td> <td> <ul style="list-style-type: none"> treat object as having zero mass tension the same at both ends of a light string </td> </tr> <tr> <td>Inextensible string – A string that does not stretch under load.</td> <td> <ul style="list-style-type: none"> acceleration is the same in objects connected by a taut inextensible string </td> </tr> <tr> <td>Smooth surface</td> <td> <ul style="list-style-type: none"> assume that there is no friction between the surface and any object on it </td> </tr> <tr> <td>Rough surface – If a surface is not smooth, it is rough.</td> <td> <ul style="list-style-type: none"> objects in contact with the surface experience a frictional force if they are moving or are acted on by a force </td> </tr> <tr> <td>Wire – Rigid thin length of metal.</td> <td> <ul style="list-style-type: none"> treated as one-dimensional </td> </tr> <tr> <td>Smooth and light pulley – all pulleys you consider will be smooth and light.</td> <td> <ul style="list-style-type: none"> pulley has no mass tension is the same on either side of the pulley </td> </tr> <tr> <td>Bead – Particle with a hole in it for threading on a wire or string.</td> <td> <ul style="list-style-type: none"> moves freely along a wire or string tension is the same on either side of the bead </td> </tr> <tr> <td>Peg – A support from which a body can be suspended or rested.</td> <td> <ul style="list-style-type: none"> dimensionless and fixed can be rough or smooth as specified in question </td> </tr> <tr> <td>Air resistance – Resistance experienced as an object moves through the air.</td> <td> <ul style="list-style-type: none"> usually modelled as being negligible </td> </tr> <tr> <td>Gravity – Force of attraction between all objects. Acceleration due to gravity is denoted by g.</td> <td> <ul style="list-style-type: none"> assume that all objects with mass are attracted towards the Earth Earth's gravity is uniform and acts vertically downwards g is constant and is taken as 9.8 m s^{-2}, unless otherwise stated in the question </td> </tr> </tbody> </table> <p style="text-align: center;">$g = 9.8 \text{ m s}^{-2}$</p> <ul style="list-style-type: none"> Students will know the SI units. Students will know that KG measures mass and not weight. Students will know how to convert between units. 	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<p>To learn how to use vectors in mechanics.</p>	<ul style="list-style-type: none"> • <i>Students will know that vector quantities are displacement, velocity, acceleration and force/weight.</i> • <i>Students will know how to fully describe motion using vectors.</i> • <i>Students will know you can describe vectors using i, j notation, where i and j are the unit vectors in the positive x and y directions</i> • <i>Students will know that the magnitude of the displacement vector.</i> • <i>Students will know that speed is the magnitude of the velocity vector.</i> 		<p>Students will need to know how to find the magnitude of a vector. Students will need to know how to find an angle of a vector.</p>	

<p>Students will know how to use the trapezium rule to approximate integration.</p>	<ul style="list-style-type: none"> • Students will know that if you cannot integrate a function algebraically, you can use a numerical method to approximate the area beneath a curve. • Students will know that to approximate the area given by $\int_a^b y dx$ you can divide the area into n equal strips. Each strip will be of width h where $h = \frac{b-a}{n}$ • Students will know that $\int_a^b y dx \approx \frac{1}{2}h(y_0 + 2(y_1 + y_2 \dots + y_{n-1}) + y_n)$ where $h = \frac{b-a}{n}$ and $y_i = f(a + ih)$ • Students will know if there answer is an overestimate (convex) or underestimate. 		<p>Students will need to know the area of a trapezium. Students will need to know how to substitute into a formula Students will need to know how to use radians.</p>	
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